AI IN AUTONOMOUS CARS

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Abstract

In this paper will cover the transformation of normal cars into the autonomous or Driverless car, problems related with it, objectives, requirements and the expected result of this step. In this paper will compare the standards and give the important comparison between conventional anddriverless cars. This AI based car will cause a huge change in human's life, we will study and examine the various impacts on society, legal and ethical challenges, and importantly environmental constraints. We will also study on the previous similar technologies and take a look the way researchers are working to make this technology even better in the future.

Keyword: AI car, self-driving, Simulation test, autonomous cars, autopilot car.

1. INTRODUCTION

Scientists and researchers are attempting to improve the quality of human life as the world changes. More people than ever before are anticipating the introduction of driverless vehicles. This car's key strength is its capacity to use contemporary artificial intelligence to understand its surroundings and make judgements on its own. To put it another way, these vehicles feature specialized sensors, CPUs, and This car's operation is handled by a database, which eliminates the need for a driver. It drives itself to the location that consumers have requested. It is the major advancement in robotics that has greatly increased the level of safety on this planet.

2. LITERATURE REVIEW

AI is a branch of computer science that analyses multiple visual inputs, including facial, object, and gesture identification, according to Rouf, Ali, and Hussain (2018). As a result, all autonomous vehicles use AI.Sun, Bebis, and Miller (2004) outlined activities like monitoring thetime it takes for a signal to travel after being emitted by sensors and reflected by an object in order to determine its distance. This includes using lasers and LIDAR. According to research, these sensors have a poor spatial resolution, a slow scanning rate, and interference from other sensors in areas of high traffic. According to Sun et al., the performance of sensors needs to be improved by utilising neural network and fuzzy logic technologies. [1] González, Reviejo, Garca, Naranjo.

3. PROBLEM DEFINITION

Several challenges need to be addressed to ensure the safe and equitable development of the Metaverse. These include technical limitations such as network latency and rendering of immersive environments, which could limit its scalability and accessibility. Privacy and security concerns are also significant, with the potential for data breaches and misuse of personal information eroding trust and participation. Furthermore, the Metaverse has the potential for addiction, which could have negative effects on users' mental health and well-being. Therefore, as the Metaverse continues to evolve, it is essential to tackle these challenges and establish frameworks for its responsible and ethical use.

4. OBJECTIVE/SCOPE

The objective of this Review paper is to study the Research paper and review on their ideas and innovation as how much is their efficient and how can the product created by them be developed even more. Also, the perspective of the people as what they want form product. The objective of autonomous car is to optimize the driving comfort and travel-duration, while always keeping within the safety limits. Human drivers analyze and try to handle the traffic situation choosing their actions not only based on current information but also based on past experience.

5. ADVANTAGE AND DISADVANTAGES

Advantages:

- a. **Decreased the quantity of accidents:** AI based Autonomous cars prevent errors happening from human because the system controls the vehicle. It leaves no opportunity for distraction, not similar to humans who are at risk of interruptions. It also uses complicated algorithms that determine the right stopping distance from one vehicle to another. Therefore, lessening the probabilities of accidents.
- b. **Lessens traffic jams:** The self-driving cars speed up traffic in part by keeping a buffer between themselves and the cars in front of them, forcing them to brake less often. Giving the algorithm control over traffic lights in a Manhattan-style traffic grid increased the number of cars passing through by 7%.
- c. **Stress-free parking:** Autonomous cars drop you off at your destination and directly park to a detected vacant parking spot. This reduce the wasting of your time and gas trying to find vacant one.
- d. **Time-saving vehicle:** As the system takes over the control, the motive force features a spare time to continue work orspend now catching up with their loved-ones without the having the fear about road safety.
- e. **Accessibility to transportation:** Senior citizens and disabled personnel are having difficulty driving. Autonomous vehicles assist them towards safe and accessible transportation.

Disadvantages:

- a. **High upfront cost:** The technology will likely come with ahigh cost for companies to get started. While platooning increases capacity, it also means purchasing the platoon. New technology is notcheap, but the ability to move four times as much and run trucks 24/7 does offer plenty of unique possibilities that could pay dividends in the future.
- b. More infrastructure: With more autonomous vehicles on the road more infrastructure will be required according to autonomous vechicles. New roads and new rules for traffic may need tobe implemented, such as a highway lane for self-driving vehicles only.
- c. Lost jobs: Many drivers may lost there jobs due to autonomous vehicle technology.

At first, this may not be a big deal as the shortage of drivers could be filled in with automatic cars. However, autonomous vehicle technology has the ability to transform the industry, which could mean a huge reduction in driving jobs.

d. Security: One of the biggest disadvantages of autonomous vehicle technology is security concerns. If a vehicle is hacked, it could become very dangerous. Even with someone inside the vehicle supervising, there's a real threat of a hacker gaining control of the vehicle and overriding controls. If driver sleep that time the car will be automatic stop Because if any failure occurred it is increase the possibility of accident.

6. ANALYSIS & FINDINGS

After study this AI technology in Cars It clear that there is two side of this technology in human life for some peoples perspective this technology may be good and for some peoples perspective it may not. After reviewing some paper I can say that the paper research by Sun, Bebis, and Miller (2004) is best as in this paper many latest sensors and radar are used in cars to make it autonomous.

7. LIMITATION & FUTURE SCOPE

The current generation of self-driving cars may be a transitional phase. The car is "autonomous" within the sense that it relies on its own onboard system - cameras, sensors, software, etc. If the roads are covered with a feet of snow, the car will lack reference points like lines on the road, curbs, and maybe even traffic signs.

The next generation of autonomous cars are "networked" cars. they'll not (only) depend on their onboard sensors, but also on road-site sensors. Signals from the sensors will be pickup by the carall told weather. The sensors will communicate with a central control system that monitors trafficand directs vehicles to the optimum route.

8. CONCLUSION

In this paper we analyse the expansion of autonomous cars of AI technology and what quite components and technologies are accustomed develop an autonomous cars and basic details about all components. Also, we've got learned benefits and problem statement a few selfdriving car. The dream of making artificial devices that reach or outperform human intelligence is many centuries old. the event of intelligent agents is making that dream come true for the researchers and yet as for the industry.

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